

# **Filtering Data using Frequency Domain Filters**

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# Overview

- Intro
  - lag operator
  - Why frequency domain?
- Fourier transform
- Data as cosine waves
- Spectrum
- Filters & I(1) processes
- Band-pass filters
- HP filter

# The big picture

In these slides we do three things

- ❶ Make clear that *stochastic* time series can be represented as a sum of *deterministic* cosine waves
- ❷ Learn some tools from frequency domain analysis
- ❸ These tools will make it possible to extract from *any* time series that part associated with the frequencies we are interested (for example business cycle analysis)

# Lag operator

$$x_{t-1} = Lx_t$$

$$x_{t-2} = Lx_{t-1} = LLx_t = L^2x_t$$

$$x_{t+1} = L^{-1}x_t$$

$$\Delta x_t = (1 - L)x_t$$

# Lag operator

$$x_t = \rho x_{t-1} + \varepsilon_t \text{ with } |\rho| < 1$$

$$x_t = \rho L x_t + \varepsilon_t$$

$$(1 - \rho L) x_t = \varepsilon_t$$

$$x_t = \frac{\varepsilon_t}{1 - \rho L}$$

# Lag operator

$$\frac{1}{1 - \rho} = 1 + \rho + \rho^2 + \rho^3 + \dots \text{ if } |\rho| < 1$$

$$\frac{1}{1 - \rho L} = 1 + \rho L + \rho^2 L^2 + \rho^3 L^3 + \dots \text{ if } |\rho L| < 1$$

# Why go to frequency domain

- ❶ Extract that part from the data that your model tries to explain
  - e.g., business cycle frequencies
- ❷ Some calculations are easier in frequency domain
  - e.g., auto-covariances of ARMA processes
  - not the focus on this lecture

# Fourier Transform

Given a sequence  $\{x_j\}_{-\infty}^{\infty}$  the Fourier transform is defined as

$$F(\omega) = \sum_{j=-\infty}^{\infty} x_j e^{-i\omega j}$$

If  $x_j = x_{-j}$  then

$$F(\omega) = x_0 + \sum_{j=1}^{\infty} x_j \left( e^{-i\omega j} + e^{i\omega j} \right) = x_0 + \sum_{j=1}^{\infty} 2x_j \cos(\omega j)$$

and the Fourier transform is a real-valued symmetric function.



# Fourier Transform

Given a continuous sequence  $x(j)$ , the Fourier transform is defined as

$$F(\omega) = \int_{j=-\infty}^{\infty} x(j) e^{-i\omega j} dj$$

# Fourier Transform

- It is just a definition!
  - which turns out to be useful
  - see links to youtube videos at the end of the slides

## Why useful?

The Fourier transform can *detect* frequency of data. Suppose, the sequences considered are time series. Specifically, consider

$$x_{A,t} = \cos(\omega_A t)$$

$$x_{B,t} = \cos(\omega_B t)$$

$$x_t = x_{A,t} + x_{B,t}$$

## Why useful?

$$\begin{aligned} & F_A(\omega) \\ = & \int_{-\infty}^{\infty} \cos(\omega_A t) e^{-i\omega t} dt \\ = & \int_{-\infty}^{\infty} \cos(\omega_A t) (\cos(-\omega t) + i \sin(-\omega t)) dt \\ = & \int_{-\infty}^{\infty} \cos(\omega_A t) \cos(-\omega t) dt + i \int_{-\infty}^{\infty} \cos(\omega_A t) \sin(-\omega t) dt \\ = & \int_{-\infty}^{\infty} \cos(\omega_A t) \cos(\omega t) dt - i \int_{-\infty}^{\infty} \cos(\omega_A t) \sin(-\omega t) dt \\ = & \begin{cases} > 0 & \text{if } \omega = \pm\omega_A \\ = 0 & \text{if } \omega \neq \omega_A \end{cases} \end{aligned}$$

## Why useful?

Because things are additive, we get

$$\begin{aligned} F(\omega) &= F_A(\omega) + F_B(\omega) \\ &= \begin{cases} > 0 & \text{if } \omega = \pm\omega_A \\ > 0 & \text{if } \omega = \pm\omega_B \\ = 0 & \text{otherwise} \end{cases} \end{aligned}$$

- $\implies$  Fourier transform of a time series selects the frequencies.
- If there is a phase shift in any of these series, then the series are no longer symmetric around  $t = 0$  and the Fourier transform would also have an imaginary part.

# Inverse Fourier Transform

- Given a Fourier Transform  $F(\omega)$ , one can back out the original sequence using

$$x_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) e^{i\omega j} d\omega = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) (\cos \omega j + i \sin \omega j) d\omega$$

and if  $F(\omega)$  is symmetric then

$$x_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} F(\omega) \cos \omega j d\omega = \frac{1}{\pi} \int_0^{\pi} F(\omega) \cos \omega j d\omega$$

- derivation is in the notes

# Thinking differently about a time series

- You can take the Fourier transform of any sequence
- So you can also take it of a time series
  - take finite analogue if time series is finite

# Thinking differently about a time series

- Finite Fourier transform of  $\{x_t\}_{t=1}^T$ , scaled by  $\sqrt{T}$

$$\tilde{x}(\omega) = \frac{1}{\sqrt{T}} \sum_{t=1}^T e^{-i\omega t} x_t.$$

- Let

$$\omega_j = -\pi + (j-1)2\pi/T \text{ for } j = 1, \dots, T+1$$



# Formulas

$\tilde{x}(\omega)$  can be expressed as

$$\tilde{x}(\omega) = |\tilde{x}(\omega)| e^{i\phi(\omega)}$$

with

$$\tilde{x}(-\omega) = |\tilde{x}(\omega)| e^{-i\phi(\omega)}$$

# Thinking differently about a time series

- The *finite* inverse Fourier transform is given by

$$\begin{aligned}
 x_t &= \frac{1}{\sqrt{T}} \sum_{|\omega_j| \leq \pi} e^{i\omega_j t} \tilde{x}(\omega_j) \\
 &= \frac{1}{\sqrt{T}} \sum_{|\omega_j| \leq \pi} |\tilde{x}(\omega)| e^{i\omega_j t} e^{i\phi(\omega)} \\
 &= \frac{\tilde{x}(0) + \sum_{0 < \omega_j \leq \pi} |\tilde{x}(\omega)| \left( e^{i(\omega_j t + \phi(\omega))} + e^{-i(\omega_j t + \phi(\omega))} \right)}{\sqrt{T}}
 \end{aligned}$$

# Thinking differently about a time series

Using

$$e^{i\delta(\omega)} = \cos \delta(\omega) + i \sin \delta(\omega)$$

or

$$e^{i\delta(\omega)} + e^{-i\delta(\omega)} = 2 \cos \delta(\omega)$$

gives

$$x_t = \frac{1}{\sqrt{T}} \left( \tilde{x}(0) + 2 \sum_{0 < \omega_j \leq \pi} |\tilde{x}(\omega_j)| \cos(\omega_j t + \phi(\omega_j)) \right)$$

This makes clear we can think of a time series as a sum of deterministic cosine waves

- $|\tilde{x}(\omega_j)|$  captures the quantitative importance of a particular frequency

# Two realizations of the same time series process

- Suppose  $x_t$  and  $y_t$  are two realizations of the same time series process, say an AR(1).
- Then the  $|\tilde{x}(\omega_j)|$  would be similar (or same if there is no sampling uncertainty)
- The random differences due to different realizations of the shocks are captured by having different phase shifts,  $\phi(\omega)$

# Thinking differently about a time series

$$x_t = \frac{1}{\sqrt{T}} \left( \tilde{x}(0) + 2 \sum_{\omega_j \leq \pi} |\tilde{x}(\omega_j)| \cos(\omega_j t + \phi(\omega_j)) \right)$$

Simple interpretation:

- $x_t$  : dependent variable ( $T$  observations)
- $\omega_j t$  :  $T$  independent variables
- get perfect fit by choosing  $|\tilde{x}(\omega_j)|$  and  $\phi(\omega_j)$
- if  $|\tilde{x}(\omega_j)|$  is high than that frequency is important for time variation  $x_t$

## (Informally) thinking about the variance

- What is the variance of  $x_t$ ?
- Focus on the case with  $E[x_t] = 0$
- $E[x_t^2]$  depends on  $E\left[\left(\sum_{\omega_j < \pi} \tilde{x}(\omega_j)\right)^2\right]$
- Fortunately,  $\lim_{T \rightarrow \infty} E[\tilde{x}(\omega_j)\tilde{x}(\omega_i)] = 0$
- variance of  $x_t$  depends just on sum of the squared  $|\tilde{x}(\omega_j)|$  terms (or on the integral in the limit)

# Spectrum

- Given a sequence  $\{\gamma_j\}_{-\infty}^{\infty}$  of autocovariances of a scalar process then the spectrum is defined as

$$S(\omega) = \frac{1}{2\pi} \sum_{j=-\infty}^{\infty} \gamma_j e^{-i\omega j} = \frac{1}{2\pi} \left( \gamma_0 + \sum_{j=1}^{\infty} 2\gamma_j \cos(\omega j) \right)$$

- And according to the inverse

$$\gamma_0 = \int_{-\pi}^{\pi} S(\omega) d\omega$$

- That is, if you integrate over all frequencies you get the variance. This is also consistent with the view that the data can be thought of as a sum of cosine waves

# Spectrum

So spectrum is just the Fourier transform of the covariances



# Spectrum of transformed series

If

$$y_t = \sum_{j=-\infty}^{\infty} b_j x_{t-j} = b(L)x_t$$

Then

$$S_y(\omega) = b(e^{-i\omega})b(e^{i\omega})S_x(\omega) = \left|b(e^{-i\omega})\right|^2 S_x(\omega)$$

- $|\cdot|$  is the modulus of the complex number
- Note that  $b(e^{-i\omega})$  is the Fourier transform of the  $b_j$  sequence
- For symmetric filters we have  $b(e^{-i\omega}) = b(e^{i\omega})$

## Examples - white noise

$$x_t = \varepsilon_t \text{ and } E[\varepsilon_t \varepsilon_{t-j}] = 0 \text{ for } j \neq 0$$

$$\begin{aligned} S(\omega) &= \frac{1}{2\pi} \sum_{j=-\infty}^{\infty} \gamma_j e^{-i\omega j} \\ &= \frac{1}{2\pi} \left( \gamma_0 + \sum_{j=1}^{\infty} 2\gamma_j \cos(\omega j) \right) \\ &= \frac{\gamma_0}{2\pi} \end{aligned}$$

## Examples - AR(1)

$$y_t = \rho y_{t-1} + x_t$$

$$y_t = \frac{x_t}{1 - \rho L}$$

$$\begin{aligned} S_y(\omega) &= \left| \frac{1}{1 - \rho e^{-i\omega}} \right|^2 S_x(\omega) \\ &= \frac{1}{1 - \rho e^{-i\omega}} \frac{1}{1 - \rho e^{+i\omega}} S_x(\omega) \\ &= \frac{1}{1 - \rho (e^{-i\omega} + e^{+i\omega}) + \rho^2} S_x(\omega) \\ &= \frac{1}{1 - 2\rho \cos \omega + \rho^2} S_x(\omega) \end{aligned}$$

# Examples - VAR(P)

$$y_t = \sum_{j=1}^J A_j y_{t-j} + x_t$$

$$y_t = \left( I - \sum_{j=1}^J A_j L^j \right)^{-1} x_t$$

$$S_y(\omega) = \left( I - \sum_{j=1}^J A_j e^{-ij\omega} \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' e^{ij\omega} \right)^{-1}$$

## Examples - VAR(P)

$$y_t = \sum_{j=1}^J A_j y_{t-j} + x_t$$

$$\begin{aligned} S_y(0) &= \left( I - \sum_{j=1}^J A_j e^{-ij \times 0} \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' e^{ij \times 0} \right)^{-1} \\ &= \left( I - \sum_{j=1}^J A_j \right)^{-1} S_x(\omega) \left( I - \sum_{j=1}^J A_j' \right)^{-1} \end{aligned}$$

This last formula is useful in calculating Heteroskedastic and Autocorrelation Consistent (HAC) variance-covariance estimators

# What is a filter?

- A filter is just a transformation of the data
- Typically with a particular purpose
  - e.g. remove seasonality or "noise"
- Filters can be expressed as

$$x_t^f = b(L)x_t$$
$$b(L) = \sum_{j=-\infty}^{\infty} b_j L^j$$

# Examples of filters

$$b(L) = 1 - L \implies x_t^f = x_t - x_{t-1}$$

$$b(L) = -\frac{1}{2}L^{-1} + 1 - \frac{1}{2}L$$

# I(0) and I(1) processes

- I(0) processes do not have trends<sup>1</sup>
- $x_t$  is I(1) if  $\Delta x_t$  is I(0)

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<sup>1</sup>I(0) processes are often referred to as stationary processes. Strictly speaking that is not correct. Stationary processes also don't have trends but also don't allow for changes in the distribution. Defining I(0) is a bit tricky and there are different definitions. A relatively easy description of an I(0) process is a stochastic process for which past errors do not accumulate.



# I(0) and I(1) processes

$$x_t = B(L) \varepsilon_t,$$

where  $\varepsilon_t$  is white noise.

- If  $x_t$  is I(1), then  $B(1) = \infty$
- If  $B(1) < \infty$ , then  $x_t$  is I(0)

(same holds is  $\varepsilon_t$  is I(0))

# Filters that induce stationarity, meaning I(0)

- Suppose that  $x_t$  is I(1). Thus

$$(1 - L)x_t = z_t$$

with  $z_t$  an I(0) process.

- Filtering gives

$$x_t^f = b(L)x_t$$

- Question: When is  $x_t^f$  I(0)?

## Filters that induce stationarity

Define  $\bar{b}(L)$  such that

$$b(L) = (1 - L)\bar{b}(L).$$

If

$$\bar{b}(1) < \infty,$$

then  $x_t^f = b(L)x_t$  is I(0) even if  $x_t$  is I(1).

$$\begin{aligned}x_t^f &= b(L)x_t \\&= (1 - L)\bar{b}(L)x_t \\&= (1 - L)\bar{b}(L)\frac{z_t}{(1 - L)} \\&= \bar{b}(L)z_t\end{aligned}$$

## Filters that induce stationarity

Suppose

$$b(L) = \sum_{j=-J}^J b_j L^j \text{ and } b(1) = 0$$

That is,  $L = 1$  is a root of the problem  $b(L) = 0$ , which means we have

$$b(L) = (1 - L)\bar{b}(L).$$

Since  $\bar{b}(L)$  is a *finite*-order polynomial, we know that

$$\bar{b}(1) < \infty.$$

Consequently,  $x_t^f = b(L)x_t$  is I(0) if  $x_t$  is I(1).

# Spectrum of filtered series

$$y_t = \sum_{j=-\infty}^{\infty} b_j x_{t-j} = b(L)x_t$$

Then

$$S_y(\omega) = b(e^{-i\omega})b(e^{i\omega})S_x(\omega) = \left|b(e^{-i\omega})\right|^2 S_x(\omega)$$

- $|\cdot|$  is the modulus of the complex number
- Note that  $b(e^{-i\omega})$  is the Fourier transform of the  $b_j$  sequence
- For symmetric filters we have  $b(e^{-i\omega}) = b(e^{i\omega})$

# Band-pass filters

$$y_t = b(L)x_t$$

Goal:

$$S_y(\omega) = \begin{cases} S_x(\omega) & \text{if } \omega_L \leq |\omega| \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

Thus we need

$$b(e^{-i\omega}) = \begin{cases} 1 & \text{if } \omega_L \leq |\omega| \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

- How to find the coefficients  $b_j$  that correspond with this?
- Since  $b(e^{-i\omega})$  is a Fourier transform we can use the inverse of the Fourier transform

# Coefficients of band-pass filters

Inverse of the Fourier transform for  $b_0$ :

$$\begin{aligned} b_j &= \frac{1}{2\pi} \int_{-\pi}^{\pi} b(e^{-i\omega}) e^{i\omega j} d\omega \\ &= \frac{1}{2\pi} \left( \int_{-\omega_H}^{-\omega_L} 1 \times e^{i\omega j} d\omega + \int_{\omega_L}^{\omega_H} 1 \times e^{i\omega j} d\omega \right) \\ &= \frac{\omega_H - \omega_L}{\pi} \end{aligned}$$

# Coefficients of band-pass filters

Inverse of the Fourier transform for  $b_j$ :

$$\begin{aligned}
 b_j &= \frac{1}{2\pi} \int_{-\pi}^{\pi} b(e^{-i\omega}) e^{i\omega j} d\omega \\
 &= \frac{1}{2\pi} \left( \int_{-\omega_H}^{-\omega_L} 1 \times e^{i\omega j} d\omega + \int_{\omega_L}^{\omega_H} 1 \times e^{i\omega j} d\omega \right) \\
 &= \frac{1}{2\pi} \left( \int_{\omega_L}^{\omega_H} (e^{i\omega j} + e^{-i\omega j}) d\omega \right) \\
 &= \frac{1}{2\pi} \int_{\omega_L}^{\omega_H} 2 \cos(\omega j) d\omega \\
 &= \frac{1}{\pi j} \left[ \sin \omega j \right]_{\omega_L}^{\omega_H} = \frac{\sin(\omega_H j) - \sin(\omega_L j)}{\pi j}
 \end{aligned}$$

Note that you can also get  $b_0$  from the last line by using l'Hopital's rule



# Properties of the band-pass filter

$$b(L) = \sum_{j=-\infty}^{\infty} b_j L^j$$

- $b(L)$  is a polynomial of  $L$ . Consider the roots to the problem:

$$b(L) = 0$$

If  $L = 1$  is a root of the problem, then we have

$$b(L) = (1 - L)\bar{b}(L) \quad \text{with } \bar{b}(1) < \infty$$

# Properties of the band-pass filter

- But  $L = 1$  is a root of our filter as long as  $\omega_L > 0$ , because then we have by construction

$$b(1) = b(e^{-i0}) = 0$$

Clearly, if you do not filter out the zero frequency then you do not induce stationarity

## More on I(1) processes

- Discussion above showed

$$x_t^f = b(L)x_t \text{ is } I(0) \text{ even if } x_t \text{ is } I(1)$$

- This is not enough to show that the filter does what it is supposed to do, which is
  - ensure the spectrum of the filtered series is zero for the excluded frequencies
  - ensure the spectrum of the filtered series equals the spectrum of the original series for the included frequencies
- The second condition requires a definition of the spectrum for I(1) processes

# Spectrum for I(1) processes

Consider an arbitrary I(1) process

$$x_t = \frac{z_t}{1 - L}$$

Let

$$x_{\rho,t} = \frac{z_t}{1 - \rho L}$$

For  $\rho < 1$  the spectrum of  $x_{\rho,t}$  is well defined

$$S_{\rho,x}(\omega) = \frac{1}{1 - 2\rho \cos(\omega) + \rho^2} S_z(\omega)$$

Define the spectrum of  $x_t$  as

$$S_x(\omega) = \lim_{\rho \rightarrow 1} S_{\rho,x}(\omega)$$

This is well defined for all  $\omega > 0$ , but not for  $\omega = 0$ .

# Filtered I(1) process

$$x_t^f = b(L)x_t$$

Let  $b(L)$  be a band-pass filter, that is,

$$b(e^{-i\omega}) = \begin{cases} 1 & \text{if } \omega_L \leq \omega \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$$

# Filtered I(1) process

- if  $\omega_L > 0$ , then it can be shown that
  - $x_t^f$  is I(0) (because as shown above we know that  $b(1) = 0$ ) and
  - $S_{x^f}(\omega) = \begin{cases} S_x(\omega) & \text{if } \omega_L \leq \omega \leq \omega_H \\ 0 & \text{o.w.} \end{cases}$
- That is, using the definition of the Spectrum for I(1) processes the filter does exactly what it is supposed to do
- Proof is simple; The only tricky thing is to prove is that

$$b(e^{-i0})S_x(0) = 0$$

## Practical Filter

- The filter constructed so far is two-sided and infinite order
- Implementable version would be to use

$$\tilde{b}(L) = \sum_{j=-J}^J b_j L^j$$

But it is not necessarily the case that

$$\tilde{b}(1) = 0$$

So instead use

$$a(L) = \sum_{j=-J}^J a_j L^j$$

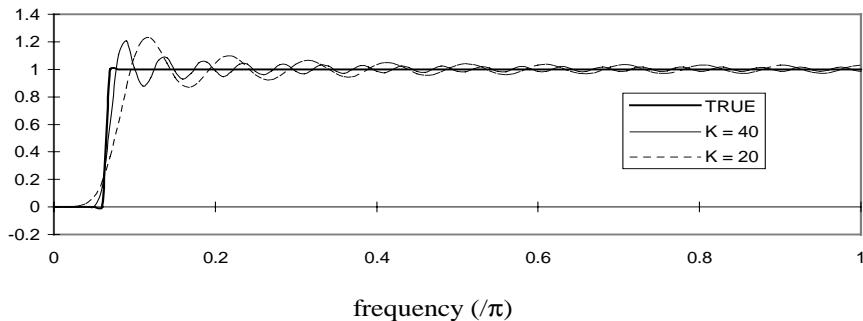
with

$$a_j = b_j + \mu \quad \text{and} \quad \mu = -\frac{\sum_{j=-J}^J b_j}{2J+1}$$

# Properties practical filter

FIGURE 3.1: SPECTRA OF FILTERED PROCESSES ( $\omega_1 = \pi/16, \omega_2 = \pi$ )

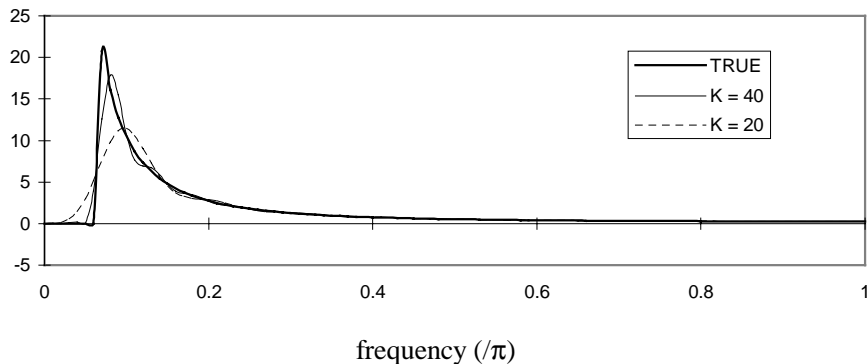
A: White Noise (Squared Gain)





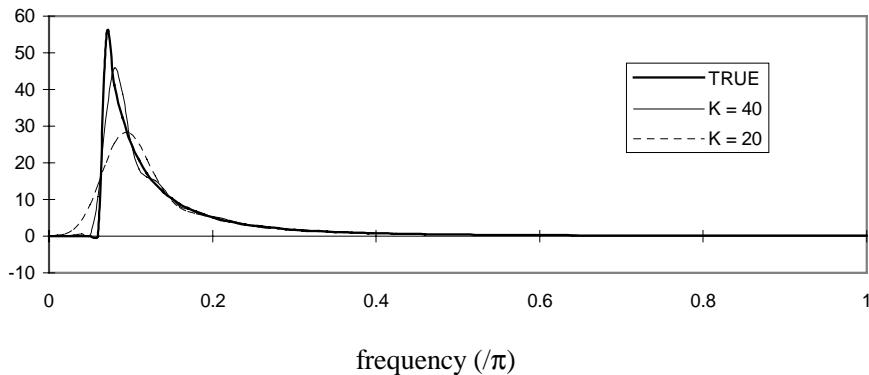
# Properties practical filter

B: AR(1) with Coefficient equal to 0.95



# Properties practical filter

C: Integrated AR(1) with Coefficient equal to 0.4



# Hodrick-Prescott Filter

- The HP trend,  $x_{\tau,t}$  is defined as follows

$$\begin{aligned} & \{x_{\tau,t}\}_{t=1}^T \\ & = \\ & \arg \min_{\{x_{\tau,t}\}_{t=1}^T} \sum_{t=2}^{T-1} (x_t - x_{\tau,t})^2 + \lambda \sum_{t=2}^{T-1} \left\{ \left[ \begin{array}{c} (x_{\tau,t+1} - x_{\tau,t}) \\ - (x_{\tau,t} - x_{\tau,t-1}) \end{array} \right]^2 \right\} \end{aligned}$$

# Hodrick-Prescott Filter

- $\lambda = 1,600$  standard for quarterly data
- the HP filter is then approximately equal to a band-pass filter with  $\omega_L = \pi/16$  and  $\omega_H = \pi$ .
  - That is, it keeps that part of the series associated with cycles that have a period less than 32 ( $=2\pi/(\pi/16)$ ) periods (i.e. quarters).

# Understanding filtered data is tricky

- Is filtered white noise serially uncorrelated?
- Are the filtered price level and filtered output positively correlated in a model with only demand shocks?  
(example below is from Den Haan 2000)

# Simple demand shock model

- Output is demand determined

$$y_t = y_t^d = D_t - P_t$$

- Demand is given by

$$(1 - \lambda_1 L) (1 - \lambda_2 L) (1 - \lambda_3 L) D_t = \varepsilon_t$$

with  $-1 < \lambda_3 < \lambda_2 < \lambda_1 \leq 1$

- Output is given by

$$y_t^s = a + bt$$

# Simple demand shock model

- Equilibrium price level  $\tilde{P}_t$  satisfies

$$\tilde{P}_t = D_t - y_t^s$$

- Actual prices adjust gradually

$$P_t = (1 - \beta) P_{t-1} + \beta \tilde{P}_t$$

# Simple demand shock model

## Solution

- Price level

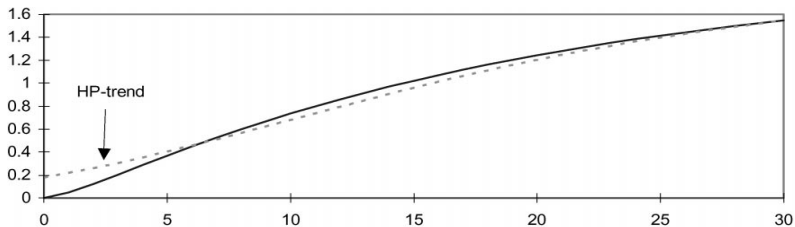
$$P_t = \frac{\beta \varepsilon_t}{(1 - (1 - \beta)L)(1 - \lambda_1 L)(1 - \lambda_2 L)(1 - \lambda_3 L)}$$

- Output

$$y_t = \frac{(1 - \beta)(1 - L)\varepsilon_t}{(1 - (1 - \beta)L)(1 - \lambda_1 L)(1 - \lambda_2 L)(1 - \lambda_3 L)}$$

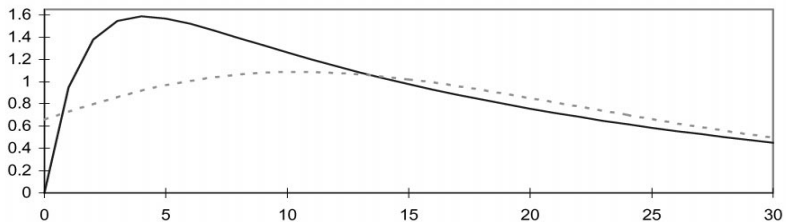


# Positive correlation for unfiltered series



A

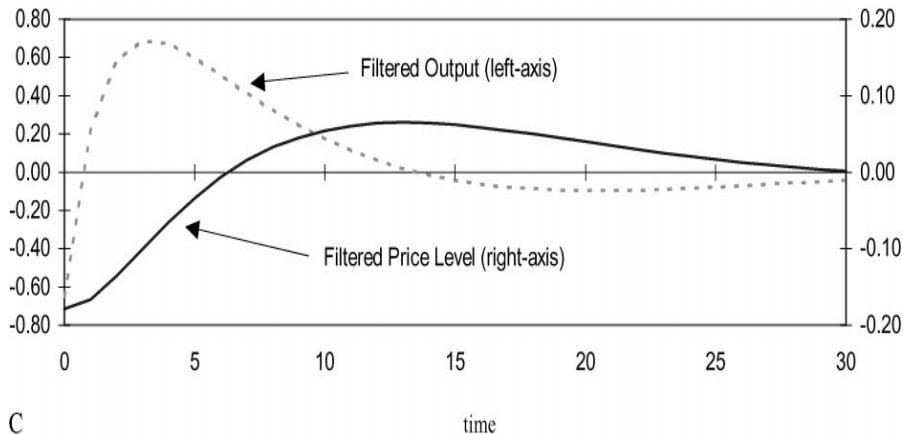
time



B

time

# Negative correlation for filtered series



C

# References

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- Den Haan, W.J., 2000, The Comovement between Output and Prices, Journal of Monetary Economics, 3-30.
- Den Haan, W.J., frequency domain and filtering, available at <http://www.wouterdenhaan.com/teach/spectrum.pdf>.

# Cool youtube videos

- <https://www.youtube.com/watch?v=spUNpyF58BY>
- <https://www.youtube.com/watch?v=1JnayXHhjlq>
- <https://www.youtube.com/watch?v=kKu6JDqNma8>