

Simulating models with heterogeneous agents

Wouter J. Den Haan
London School of Economics

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Individual agent

- Subject to employment shocks ($\varepsilon_{i,t} \in \{0, 1\}$)
- Incomplete markets
 - only way to save is through holding capital
 - borrowing constraint $k_{i,t+1} \geq 0$
- Competitive firms, thus competitive prices
 - $w_t = (1 - \alpha) z_t \left(\frac{K_t}{\bar{L}_t} \right)^\alpha$
 - $r_t = \alpha z_t \left(\frac{K_t}{\bar{L}_t} \right)^{\alpha-1}$

Individual agent

$$\max_{\{c_{i,t}, k_{i,t+1}\}_{t=0}^{\infty}} E \sum_{t=0}^{\infty} \beta^t \ln(c_{i,t})$$

s.t.

$$c_{i,t} + k_{i,t+1} = r_t k_{i,t} + (1 - \tau_t) w_t \bar{l} \varepsilon_{i,t} + \mu w_t (1 - \varepsilon_{i,t}) + (1 - \delta) k_{i,t}$$

$$k_{i,t+1} \geq 0$$

Laws of motion

- z_t can take on two values
- $\varepsilon_{i,t}$ can take on two values
- probability of being (un)employed depends on z_t
- transition probabilities are such that unemployment rate only depends on current z_t
- Thus $u_t = u^b$ if $z_t = z^b$ and $u_t = u^g$ if $z_t = z^g$ with $u^b > u^g$.

Complexity of individual problem

- for given process of r_t and w_t this is a relatively simple problem
- state variables?
- constraint?

What aggregate variables do agents care about?

- r_t and w_t
- They only depend on aggregate capital stock and z_t
- !!! This is not true in general for equilibrium prices
- Agents are interested in all information that forecasts K_t
- Thus, complete cross-sectional distribution of employment status and capital levels matters

Equilibrium

- Continuum of agents
- Individual policy functions that solve the agent's maximization problem
- A wage and a rental rate given by equations above.
- A transition law for the cross-sectional distribution of capital, that is consistent with the investment policy function.
 - f_t = beginning-of-period cross-sectional distribution of capital and the employment status after the employment status has been realized.

$$f_{t+1} = Y(z_{t+1}, z_t, f_t)$$

Two different ways to go

- Simulate a panel with a large number of agents
 - This uses Monte Carlo integration to calculate cross-sectional moments
- Use tools from numerical literature
 - grid method that does not require the inverse of the policy function
 - grid method that requires the inverse of the policy function
 - non-grid method

What is given?

- A policy function $k'(k_{i,t}, \varepsilon_{i,t}, s_t)$
 - s_t : the aggregate state variables
- initial distribution for $t = 1$
 - characterizes the density of capital holdings of the employed and unemployed.

Grid method I

- Fine grid with nodes: $\kappa_i, i = 0, 1, \dots, \chi$
- Only mass AT grid points
 - $p_{i,t}^\varepsilon$: mass of agents with $k_t^\varepsilon = \kappa_i, i = 0, 1, \dots, \chi$
 - ε : employment status
 - no mass in between grid points
- If $k_i' \geq 0$ is binding $\implies p_{0,t}^\varepsilon > 0$ (and CDF has some jumps at other points)

Grid method I

- Fix employment status
 - remain within the period t for now
- Nodes correspond with *beginning-of-period t* distribution

Grid method I

- focus on node j with mass $p_t^{\varepsilon, j}$ and capital value κ_j
- find i such that $k'(\kappa_j, \varepsilon, \cdot)$ satisfies

$$\kappa_{i-1} < k'(\kappa_j, \varepsilon, \cdot) \leq \kappa_i$$

- if $k'(\kappa_j, \varepsilon, \cdot) > \kappa_\chi$, $i = \chi$

Grid method I

- Set end-of-period fractions:

$$f_t^{\varepsilon,i} = 0 \quad \forall i$$

- Go through all nodes and allocate beginning-of-period $p_t^{\varepsilon,j}$ to end-of-period $f_t^{\varepsilon,i}$:

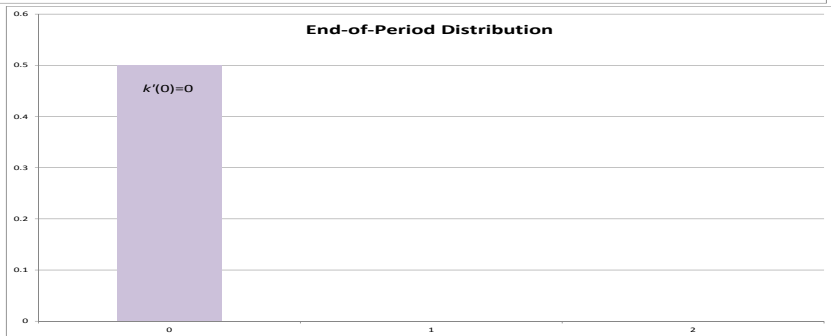
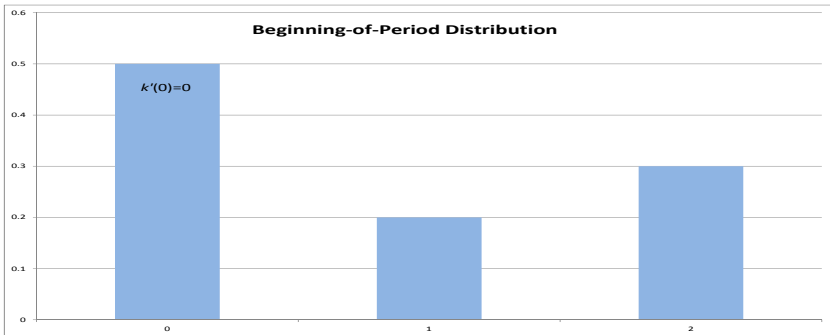
$$\omega_t^{i,j} = \frac{k'(\kappa_j, \varepsilon, \cdot) - \kappa_{i-1}}{\kappa_i - \kappa_{i-1}}$$

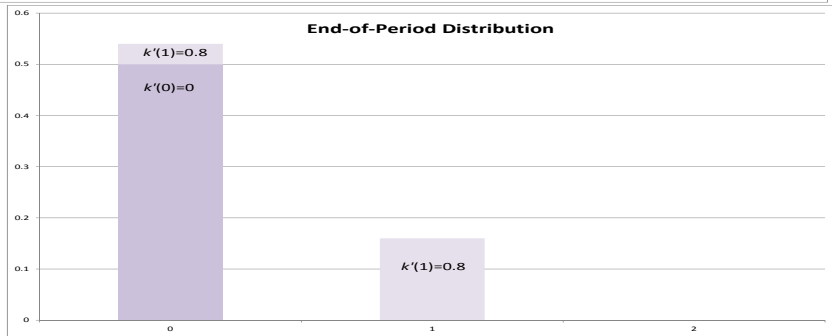
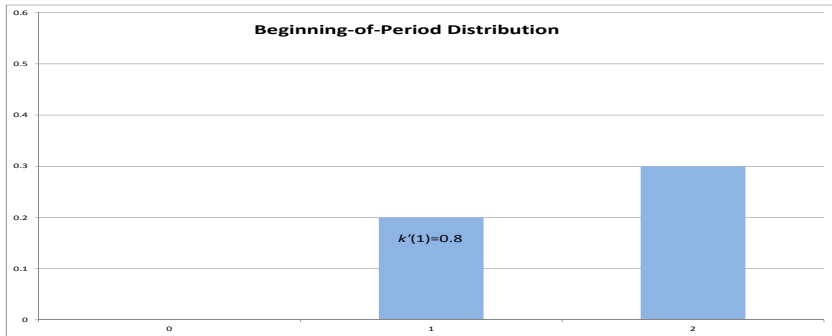
if $k'(\kappa_j, \varepsilon, \cdot) \leq \kappa_\chi$ then

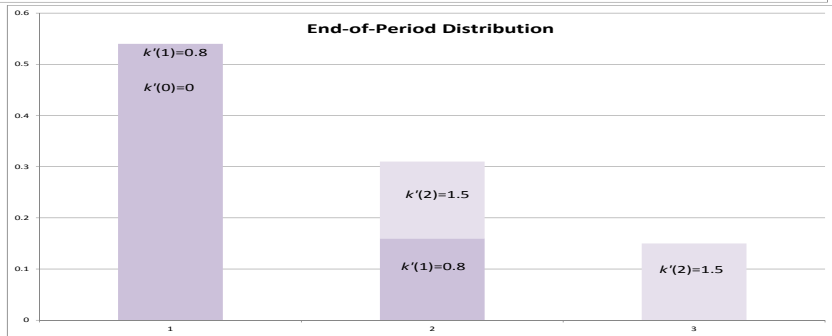
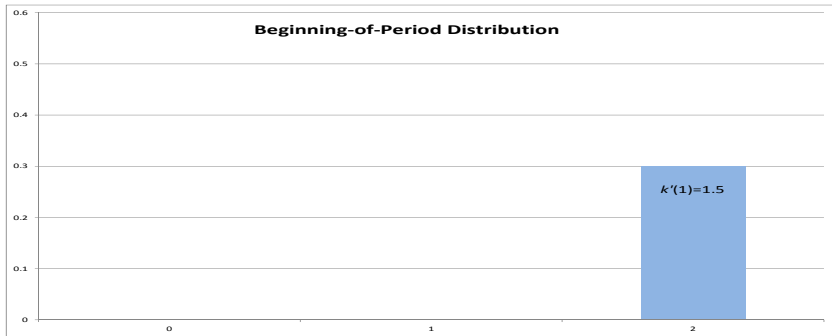
$$f_t^{\varepsilon,i-1} = f_t^{\varepsilon,i-1} + p_t^{\varepsilon,j} \left(1 - \omega_t^{i,j}\right)$$

$$f_t^{\varepsilon,i} = f_t^{\varepsilon,i} + p_t^{\varepsilon,j} \omega_t^{i,j}$$

if $k'(\kappa_j, \varepsilon, \cdot) > \kappa_\chi$ then $f_t^{\varepsilon,\chi} = f_t^{\varepsilon,\chi} + p_t^{\varepsilon,j}$







Grid method I

- Use transition laws to go from end-of-period t to beginning-of-period $t + 1$ distribution

Next period's distribution?

- $g_{\varepsilon_t \varepsilon_{t+1} z_t z_{t+1}}$ = mass of agents with employment status ε_t that have employment status ε_{t+1} , conditional on the values of z_t and z_{t+1}
- For each combination of values of z_t and z_{t+1} we have

$$g_{00z_t z_{t+1}} + g_{01z_t z_{t+1}} + g_{10z_t z_{t+1}} + g_{11z_t z_{t+1}} = 1$$

We then have

$$p_{t+1}^{\varepsilon,i} = \frac{g_{0\varepsilon z_t z_{t+1}}}{g_{0\varepsilon z_t z_{t+1}} + g_{1\varepsilon z_t z_{t+1}}} f_t^{0,i} + \frac{g_{1\varepsilon z_t z_{t+1}}}{g_{0\varepsilon z_t z_{t+1}} + g_{1\varepsilon z_t z_{t+1}}} f_t^{1,i}$$

Grid method II

- Distribution uniformly distributed between grid points
 - CDFs: two piece-wise linear splines, $P_t^{\varepsilon=0}(k)$ and $P_t^{\varepsilon=1}(k)$

Grid method II

- Calculate the end-of-period distribution as follows
 - nodes correspond to the *end-of-period* distribution
 - go through the nodes, κ_i , one by one
 - calculate the beginning-of-period capital stock at which the agent would have chosen the value at the grid point, $x_t^{\varepsilon,i} = k'^{inv}(\kappa_i, \varepsilon_t, s_t)$
 - CDF at grid point is equal to $P_t^\varepsilon(x_t^{\varepsilon,i})$ (Note the two time subscripts)

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$$F_t^{\varepsilon,i} = \int_0^{x_t^{\varepsilon,i}} dP_t^\varepsilon(k) = \sum_{i=0}^{\bar{i}_\varepsilon} p_t^{\varepsilon,i} + \frac{x_t^{\varepsilon,i} - \kappa_{\bar{i}_\varepsilon}^-}{\kappa_{1+\bar{i}_\varepsilon}^- - \kappa_{\bar{i}_\varepsilon}^-} p_t^{\varepsilon, \bar{i}_\varepsilon + 1},$$

where $\bar{i}_\varepsilon = \bar{i}(x_t^{\varepsilon,i})$ is the largest value of i such that $\kappa_i \leq x_t^{\varepsilon,i}$

- Calculate next period's beginning-of-period distribution using the transtion laws

Next period's distribution?

$$P_{t+1}^{\varepsilon,i} = \frac{g_{0\varepsilon z_t z_{t+1}}}{g_{0\varepsilon z_t z_{t+1}} + g_{1\varepsilon z_t z_{t+1}}} F_t^{0,i} + \frac{g_{1\varepsilon z_t z_{t+1}}}{g_{0\varepsilon z_t z_{t+1}} + g_{1\varepsilon z_t z_{t+1}}} F_t^{1,i}$$

and

$$\begin{aligned} p_{t+1}^{\varepsilon,0} &= P_{t+1}^{\varepsilon,0} \\ p_{t+1}^{\varepsilon,i} &= P_{t+1}^{\varepsilon,i} - P_{t+1}^{\varepsilon,i-1} \end{aligned}$$

Parameterized cross-sectional distribution

- Grid methods are likely to require a lot of nodes (1000 is typical)
- For some procedures that is costly
- Not clear you need such precise information

Parameterized cross-sectional distribution

- Grid methods are likely to require a lot of nodes (1000 is typical)
- For some procedures that is costly
- Not clear you need such precise information
- Algan, Allais, and Den Haan (2006) propose to use polynomials
 - $P(k; \rho_t)$ is a polynomial with in period $t = 1$ coefficients equal to ρ_1
 - Using Simpson quadrature to calculate end-of-period moments
 - Use transition laws to calculate next period's beginning-of-period moments
- You need a way to find ρ_2 given values for moments in period 2

Fitting a distribution given moments: Approach I

- Find N elements of ρ such that

$$\int_0^{\infty} [k - m(1)] P(k; \rho) dk = 0$$

$$\int_0^{\infty} [(k - m(1))^2 - m(2)] P(k; \rho) dk = 0$$

...

$$\int_0^{\infty} [(k - m(1))^N - m(N)] P(k; \rho) dk = 0$$

$$\int_0^{\infty} P(k; \rho) dk = 1$$

Fitting a distribution given moments: Approach II

- Use an alternative functional form

- $$P(k; \rho) = \rho_0 \exp \left(\begin{array}{c} \rho_1 [k - m(1)] + \\ \rho_2 [(k - m(1))^2 - m(2)] + \dots + \\ \rho_N [(k - m(1))^N - m(N)] \end{array} \right)$$

Fitting a distribution given moments: Approach II

- Find coefficients ρ using
-

$$\min_{\rho_1, \rho_2, \dots, \rho_N} \int_0^{\infty} P(k, \rho) dk$$

- The first-order conditions correspond exactly to the condition that the first N moments of $P(k, \rho)$ should correspond to the set of specified moments.
- ρ_0 is determined by the condition that the density integrates to one.

Fitting a distribution given moments: Approach II

- The Hessian (times ρ_0) is given by

$$\int_0^{\infty} X(m(1), \dots, m(N)) X(m(1), \dots, m(N))' P(k, \rho) dk, \quad (1)$$

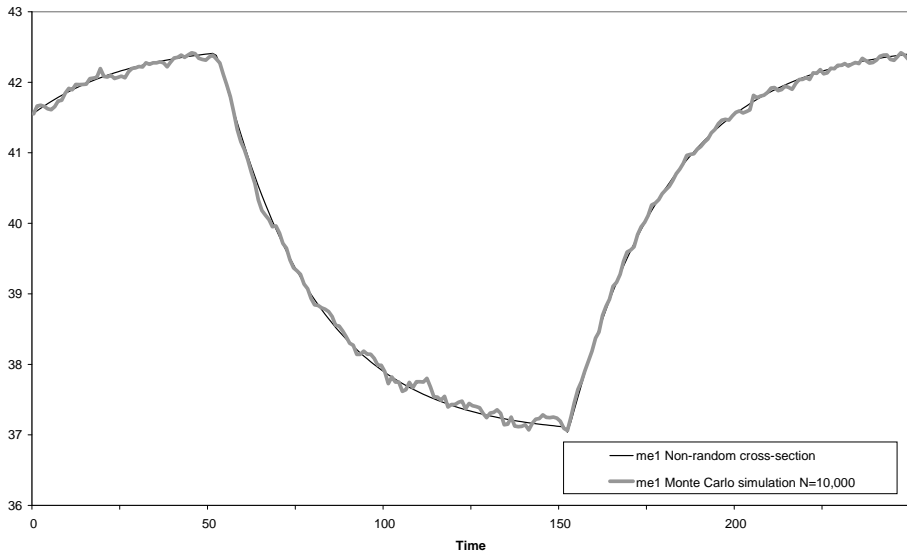
where X is an $(N \times 1)$ vector and the i^{th} element is given by

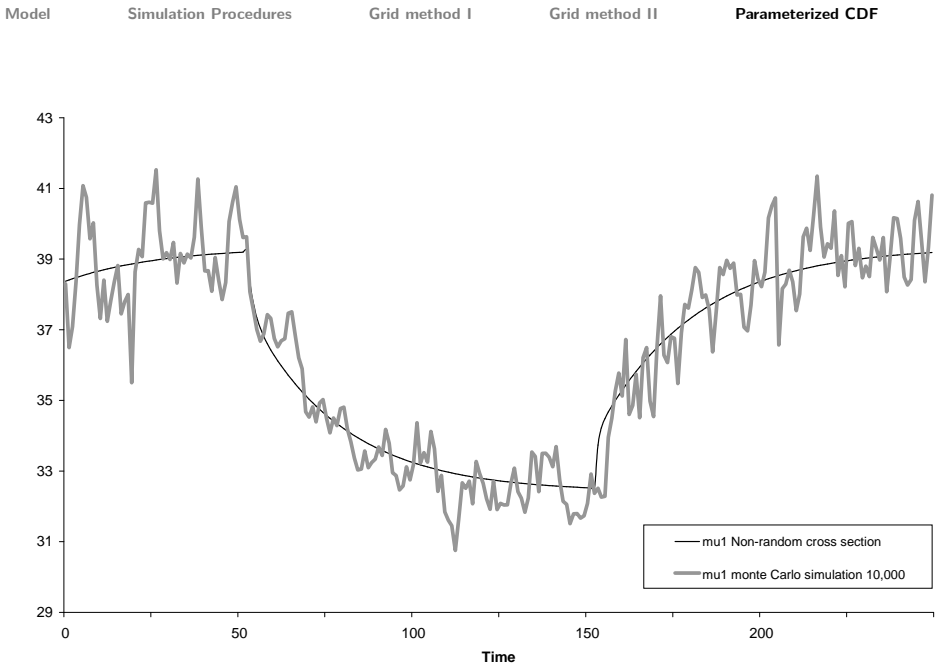
$$\begin{aligned} & (k - m(1)) \quad \text{for } i = 1 \\ & (k - m(1))^i - m(i) \quad \text{for } i > 1 \end{aligned} \quad (2)$$

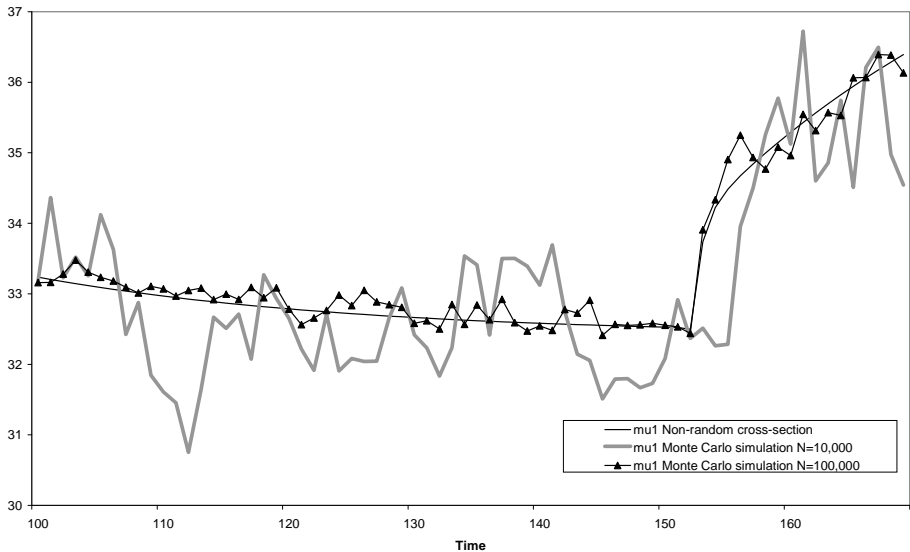
Does it make a difference?

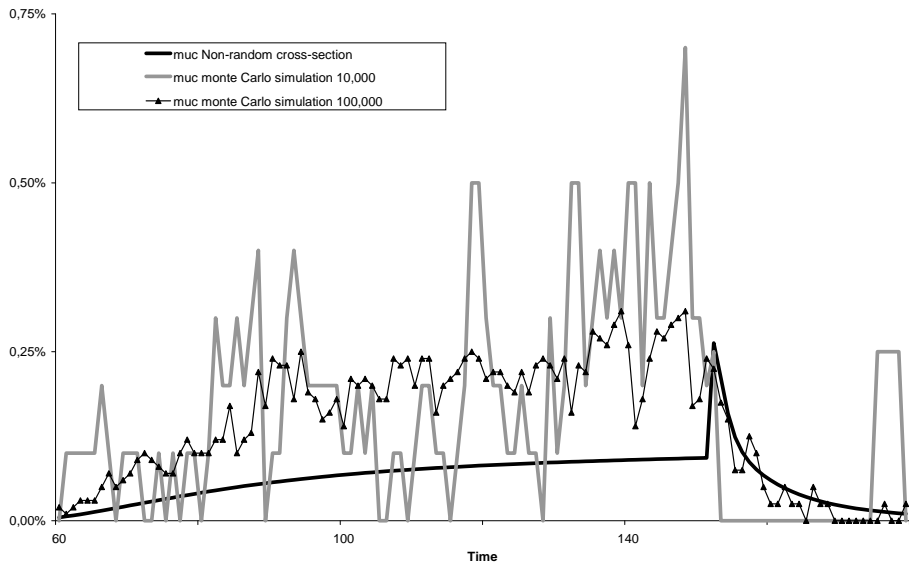
- Numerical procedure with a continuum of agents
- What if you really do like to simulate a panel with a finite number of agents?
 - Impose truth as much as possible: if you have 10,000 agents have exactly 400 (1,000) agents unemployed in a boom (recession)
 - Even then sampling noise is non-trivial
 - This is done in the graphs below, but still the results are not accurate

Simulation and sampling noise









References

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